

Reactive Power Optimization Using Quantum Particle Swarm Optimization

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Abstract: Problem statement: The problem of controlling a power system is not an easy task; it is subjected to various constraints. There are at risks of voltage instability problems due to highly stressed operating conditions caused by increased load demand and other constraints in the power system network. **Approach:** This study presents the implementation of Quantum Particle Swarm Optimization (QPSO) in solving the Reactive Power Optimization (RPO) problem. The main aim of this algorithm is the minimization of the real power loss and to improvise the voltage in the system. In this new algorithm, the particles were made to perform studies on itself and also the best ones in the system. **Results:** The implementations of QPSO were carried on modified IEEE 14 bus system for obtaining solution to the reactive power optimization and the output results are found predominant with classical PSO. **Conclusion:** This technique is used to find the best solution and also the convergence time is reduced. The proposed QPSO method is demonstrated and results are compared with traditional optimization methods.

Key words: Quantum Particle Swarm Optimization (QPSO), optimal reactive power control, Reactive Power Optimization (RPO), conditions caused, found predominant

INTRODUCTION

The main need of Reactive Power Optimization and Voltage Control is to improvise the voltage stability in the system and to minimize the losses. The power systems are provided with a number of voltage controlling devices such as generators, tap changing transformers, shunt capacitors/reactors, synchronous condensers and static VAR compensators etc. By varying the load or network configuration, a real time control of these devices will increase the problem. The conventional PSO can handle only continuous controls. QPSO method can be easily extended to handle discrete controls. This paper describes about QPSO algorithm and its application to RPO problem considering both continuous and discrete controls (Ciuprina *et al.*, 2002).

Optimal reactive power control problem: The primary objective of Reactive Power Optimization is to reduce system power losses and to obtain the setting of various controls, for the same. The real power loss is a non-linear function of bus voltage and its corresponding phase angles. It is a function of its control variables (Ning *et al.*, 2007) Eq. 1:

$$\text{Min} P_L = \sum G_k [V_i^2 + V_j^2 - 2V_i V_j \cos(\alpha_i - \alpha_j)] \quad (1)$$

The number of lines in the network is denoted by K. The above function involves various constraints for its minimization. Eq. 2-4:

$$0 = P_{gi} - P_{di} - V_i \sum V_j (G_{ij} \cos \theta_{ij} + B_{ij} \sin \theta_{ij}) \quad (2)$$

$$0 = Q_{gi} - Q_{di} - V_i \sum V_j (G_{ij} \sin \theta_{ij} + B_{ij} \cos \theta_{ij}) \quad (3)$$

$$\begin{aligned} Q_{ci} \min < Q_{ci} < Q_{ci} \max_{i \in n_c} \\ Q_{gi} \min < Q_{ci} < Q_{ci} \max_{i \in n_g} \end{aligned} \quad (4)$$

$$T_k \min < T_k < T_k \max_{k \in n_c}$$

$$V_i \min < V_i < V_i \max_{i \in n}$$

Here n is the total number of buses, n_g and n_c are number of generator and reactive sources, n_t are the number of tap changers. Power flow Eq. 2 and 3 are used as equality constraints, reactive power source

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installation restrictions, reactive generation restrictions, transformer tap-setting restrictions, bus voltage restrictions (4) are used as inequality constraints (Sun *et al.*, 2005; Platel *et al.*, 2009).

MATERIALS AND METHODS

Insight of particle swarm optimization: Particle Swarm Optimization is one of the computation technique to solve RPO problem. It is based on the concept of social behavior of organisms like school of fish etc. A flock of birds has its own objective function. (Wong and Dong, 2008). Each particle knows its own best value (pbest) and its XY position. Each particle knows the best value in their group known as gbest. Based on their velocity and distance between their best values (pbest and gbest), their position can be attained and modified. The velocity of each particle represents their modification. The velocity is modified with respect to the following equation. Eq. 5:

$$V^{k+1} = w_i V^k + c_1 r_1 (pbest_i - X_i^k) + c_2 r_2 (gbest_i - X_i^k) \quad (5)$$

Where:

- V^k = Current velocity of the particle i at iteration k
- V^{k+1} = Modified velocity of particle
- r_1, r_2 = Random numbers between 0 and 1
- X_i^k = Current position of particle i at iteration k
- $Pbest_i$ = Pbest of particle
- $Gbest_i$ = Gbest of the group
- w_i = Weight function for velocity of particle
- c_i = Weight coefficients for each term

From the above equation a certain velocity that gets close to pbest and gbest is calculated. The current position of the particle can be modified by the following Eq. 6:

$$X_i^{k+1} = X_i^k + V^{k+1} \quad (6)$$

This search procedure is called as Classical Particle Swarm Optimization (Classical PSO).

Characteristics of QPSO: The primary objective of RPO problem is reduction in the system power losses and to obtain the setting of various controls, for the same. The real power loss is a non-linear function of bus voltage magnitudes and phase angles. Based on the problem of traditional PSO trapping into local optima, Quantum theory is introduced into PSO to strengthen the particle diversities and to avoid the premature convergence. The QPSO algorithm has better convergence characteristics than the classical method.

Table 1: Comparison of QPSO and classical PSO

Variable	Classical PSO	QPSO
Voltage	1.0300	0.97
No. of iteration	75.0000	50.00
Time taken	15.7000	4.50
Power loss	81.4657	68.3213

Table 2: Power loss with respect to iteration

Iteration Time (sec)	Generation Count	PQ Generated power (MW)	Ploss (MW)
0.64073	30	2000	13.4
0.62822	53	3200	12.8
0.63766	54	4500	11.0
0.62974	85	5400	10.2
0.64577	92	6900	7.3
0.63364	110	7600	7.5
0.00017	115	8550	3.2

The power loss and the number of iterations required to reach optimal value are comparatively less than the classical approach. The comparative results between classical PSO and QPSO is represented in Table 1. This algorithm shows that it has better convergence, stronger optimal ability and better global searching capability than PSO (Pant *et al.*, 2007).

Quantum computing is a newly introduced theory based on the concepts from quantum mechanics and computer science. The origin of quantum computing dates back to the 80's when Richard Feynman found that certain quantum mechanical results cannot be effectively simulated on a personal computer. During 1990's, quantum computing has attracted worldwide interest and has motivated researchers to work on it, as it appears more effective and efficient than the traditional methods. One of the striking features of QPSO is parallel processing which can be used to solve combinatorial optimization problems and reduces the complexity. (Layeb and Saidouni 2007).

The Quantum inspired Particle Swarm Optimization (QPSO) is a recent optimization technique which is based on quantum mechanics. Similar to an evolutionary algorithm, QPSO also relies on the representation of the individual, the evaluation function and the population dynamics. QPSO represents the individual for a given problem and finally solution can be obtained. The RPO problem can be effectively solved by using this technique. The power loss with respect to the iteration is shown in Table 2. From the table we can find the Generation count for power loss and the power generated for each iteration.

Formulation of RPO problem: In order to use QPSO algorithm to solve the RPO problem, the following control variables are considered:

- Generator reactive powers
- Generator voltage magnitudes

Of the above controls considered, the Generator reactive powers and voltage magnitudes are considered as continuous, whereas the tap settings of transformers and shunt reactive sources are considered as discrete controls. So, the particles position vector is given by Eq.7:

$$X = Q1,..Qn_g, v1,..vn_g, t1,..tn_t, Q1,..Qn_c \quad (7)$$

Where:

- n_g = Is no. of generator buses
- n_t = Is no. of tap settings
- n_c = Is no. of shunt reactive sources

The steps using QPSO to solve loss control problem is represented here. The pseudo code of the procedure is as follows (Liu *et al.*, 2006; 2005):

- For each particle, initialize quantum particle of the swarm(population).
- Calculate the mean best (mbest) from the equation
- Update the position of the particle in the swarm
- Update pbest value
- Update gbest value
- Continue the iteration till maximum criteria is reached.

The procedure for implementing the QPSO is given by the following steps (Sun *et al.*, 2004).

Step1: Initialization of swarm positions: Initialize a population with random positions in the n-dimensional problem space using a uniform probability distribution function.

Step2: Evaluation of particle's fitness. Comparison to pbest (personal best): Compare each particle's fitness with its pbest value.

Step3: Comparison to gbest (global best): Compare the fitness with the population's overall pbest and updating of global point: Calculate the Mbest

Step4: Repeating the evolutionary cycle: Loop to Step 2 until a stop criterion is reached.

RESULTS AND DISCUSSION

The proposed model has been applied to modified IEEE 14 bus system as shown in Fig 1. The QPSO algorithm is tested on modified IEEE 14 bus system and the results obtained are tabulated. The ORPC problem is solved by QPSO. The Particle represents the controls used in the ORPC problem. The result shows that there is optimized loss and controls with better convergence characteristic. The parameters considered are:

- Voltages of generators at Buses 6 and 5
- Tap settings of both transformers
- VAR's of shunt capacitors at Buses 1 and 3.

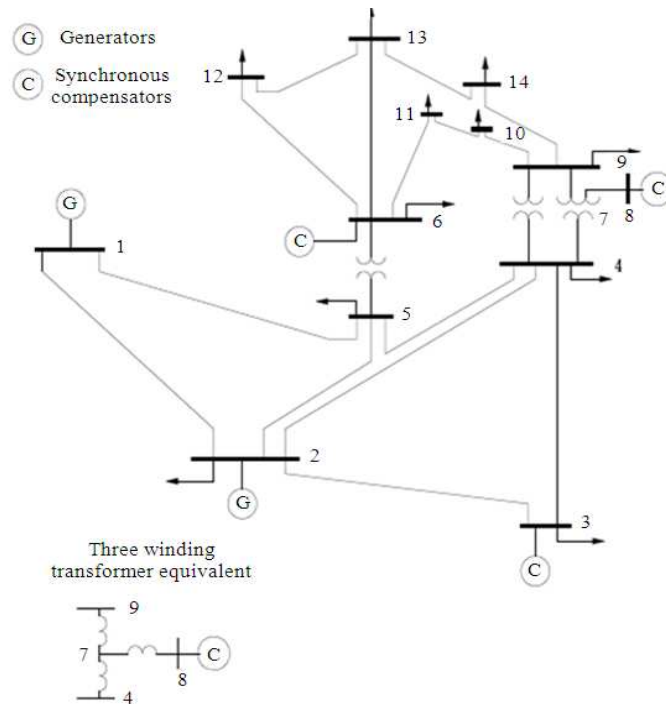


Fig. 1: Modified IEEE 14 bus system

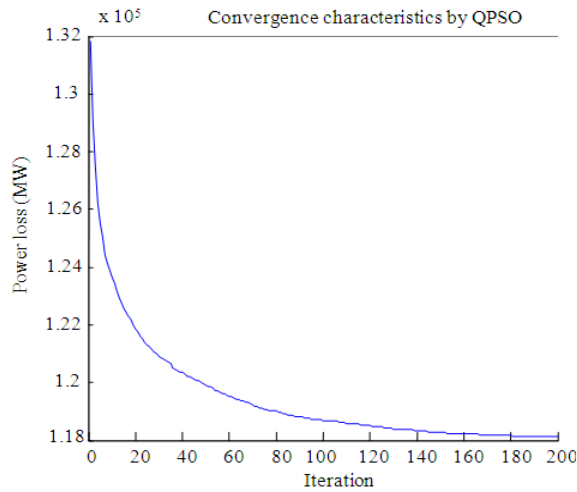


Fig. 2: Convergence characteristics of QPSO

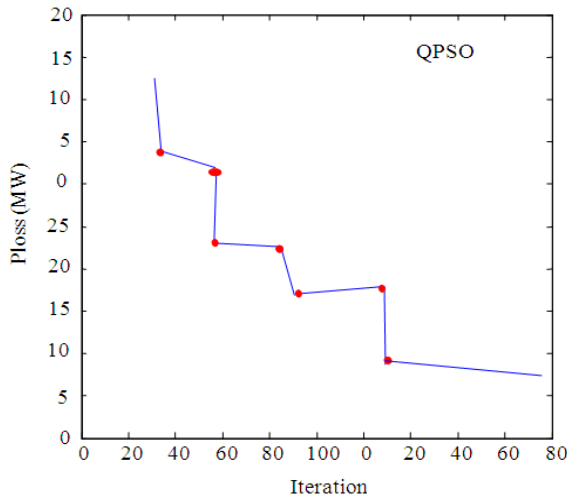


Fig. 3: Power loss characteristics by QPSO

Table 3: Comparison of the simulation results

Variable	Linear method	Classical PSO	QPSO
Reactive power	223.456	217.666	207.431
Generation reactive power	44.567	39.126	36.635
Loss total real power	143.678	135.913	128.454
Loss voltage	1.560	1.020	0.96

The comparison of various parameters like real power loss and voltage loss between QPSO and other conventional methods are represented in Table 3. From the table it shows that QPSO is highly efficient algorithm to reach global optimal value. The convergence characteristics is shown in Fig 2 and the power loss characteristics are shown in Fig 3. It clearly depicts that the convergence rate is fast and hence QPSO is an effective technique for optimization.

The reactive power controlling devices are set to minimize the system real power losses and maintain the dependent variables within limits.

CONCLUSION

The developed algorithm has been tested on modified IEEE 14 bus system for ORPC. The results using QPSO and Classical PSO are compared. The numerical results show the competitiveness of developed QPSO over Classical PSO. In Classical PSO, in the initial stages the particles converge very quickly, however, as the iteration goes on, particles become very similar and almost have no ability to explore new areas. The results justify the fact that by considering the neighbouring particle the Global solution is enhanced and speed of convergence is achieved.

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